

2	EE402PC	Electrical Machines – II	3	1	0	4
3	EE403PC	Digital Electronics	3	0	0	3
4	EE404PC	Control Systems	3	1	0	4
5	EE405PC	Power System - I	3	0	0	3
6	EE406PC	Digital Electronics Lab	0	0	2	1
7	EE407PC	Electrical Machines Lab - II	0	0	2	1
8	EE408PC	Control Systems Lab	0	0	2	1
9	*MC409	Constitution of India	3	0	0	0
		Total Credits	18	3	6	21

III YEAR I SEMESTER

S. No.	Course Code	Course Title	L	T	P	Credits
1	EE501PE	Power Electronics	3	1	0	4
2	EE502PE	Power System-II	3	1	0	4
3	EE503PE	Measurements and Instrumentation	3	1	0	4
4		Professional Elective-I	3	0	0	3
5	SM504MS	Business Economics and Financial Analysis	3	0	0	3
6	EE505PC	Power System Simulation Lab	0	0	2	1
7	EE506PC	Power Electronics Lab	0	0	2	1
8	EE507PC	Measurements and Instrumentation Lab	0	0	2	1
9	EN508HS	Advanced Communication Skills Lab	0	0	2	1
10	*MC510	Intellectual Property Rights	3	0	0	0
		Total Credits	18	3	8	22

III YEAR II SEMESTER

S. No	Course Code	Course Title	L	T	P	Credits
1		Open Elective-I	3	0	0	3
2		Professional Elective-II	3	0	0	3
3	EE601PC	Signals and Systems	2	1	0	3
4	EE602PC	Microprocessors & Microcontrollers	3	0	0	3
5	EE603PC	Power System Protection	3	1	0	4
6	EE604PC	Power System Operation and Control	3	0	0	3
7	EE605PC	Power System Lab	0	0	2	1
8	EE606PC	Microprocessors & Microcontrollers Lab	0	0	2	1
9	EE607PC	Signals and Systems Lab	0	0	2	1
10	*MC609	Environmental Science	3	0	0	0
		Total Credits	20	2	6	22

***MC609 - Environmental Science – Should be Registered by Lateral Entry Students Only.**

IV YEAR I SEMESTER

S. No.	Course Code	Course Title	L	T	P	Credits
1		Open Elective-II	3	0	0	3
2		Professional Elective-III	3	0	0	3
3		Professional Elective-IV	3	0	0	3
4	SM701MS	Fundamentals of Management for Engineers	3	0	0	3
5	EE701PC	Electrical & Electronics Design Lab	1	0	4	3

EE611PE: OPTIMIZATION TECHNIQUES (Professional Elective - III)**B.Tech. III Year II Sem.**

L	T	P	C
3	0	0	3

Prerequisite: Mathematics –I, Mathematics –II**Course Objectives:**

- To introduce various optimization techniques i.e classical, linear programming, transportation problem, simplex algorithm, dynamic programming
- Constrained and unconstrained optimization techniques for solving and optimizing an electrical and electronic engineering circuits design problems in real world situations.
- To explain the concept of Dynamic programming and its applications to project implementation.

Course Outcomes: After completion of this course, the student will be able to

- explain the need of optimization of engineering systems
- understand optimization of electrical and electronics engineering problems
- apply classical optimization techniques, linear programming, simplex algorithm, transportation problem
- apply unconstrained optimization and constrained non-linear programming and dynamic programming
- Formulate optimization problems.

UNIT - I

Introduction and Classical Optimization Techniques: Statement of an Optimization problem – design vector – design constraints – constraint surface – objective function – objective function surfaces – classification of Optimization problems.

Classical Optimization Techniques: Single variable Optimization – multi variable Optimization without constraints – necessary and sufficient conditions for minimum/maximum – multivariable Optimization with equality constraints.

Solution by method of Lagrange multipliers – Multivariable Optimization with inequality constraints – Kuhn – Tucker conditions.

UNIT - II

Linear Programming: Standard form of a linear programming problem – geometry of linear programming problems – definitions and theorems – solution of a system of linear simultaneous equations – pivotal reduction of a general system of equations – motivation to the simplex method – simplex algorithm.

Transportation Problem: Finding initial basic feasible solution by north – west corner rule, least cost method and Vogel's approximation method – testing for optimality of balanced transportation problems.

UNIT - III

Unconstrained Non-linear Programming: One dimensional minimization methods, Classification, Fibonacci method and Quadratic interpolation method

Unconstrained Optimization Techniques: Uni-variant method, Powell's method and steepest descent method.

UNIT - IV

Constrained Non-linear Programming: Characteristics of a constrained problem - classification - Basic approach of Penalty Function method - Basic approach of Penalty Function method - Basic approaches of Interior and Exterior penalty function methods - Introduction to convex programming problem.

UNIT - V

Dynamic Programming: Dynamic programming multistage decision processes – types – concept of sub optimization and the principle of optimality – computational procedure in dynamic programming – examples illustrating the calculus method of solution - examples illustrating the tabular method of solution.

TEXT BOOKS:

1. Singiresu S. Rao, Engineering Optimization: Theory and Practice by John Wiley and Sons, 4th edition, 2009.
2. H. S. Kasene & K. D. Kumar, Introductory Operations Research, Springer (India), Pvt. Ltd., 2004

REFERENCE BOOKS:

1. George Bernard Dantzig, Mukund Narain Thapa, "Linear programming", Springer series in operations research 3rd edition, 2003.
2. H. A. Taha, "Operations Research: An Introduction", 8th Edition, Pearson/Prentice Hall, 2007.
3. Kalyanmoy Deb, "Optimization for Engineering Design – Algorithms and Examples", PHI Learning Pvt. Ltd, New Delhi, 2005.

EE612PE: POWER SEMICONDUCTOR DRIVES (Professional Elective - II)**B.Tech. III Year II Sem.**

L	T	P	C
3	0	0	3

Prerequisite: Power Electronics, Electrical Machines – I, Electrical Machines – II**Course Objectives:**

- To introduce the drive system and operating modes of drive and its characteristics
- To understand Speed – Torque characteristics of different motor drives by various power converter topologies
- To appreciate the motoring and braking operations of drive
- To differentiate DC and AC drives

Course Outcomes: After completion of this course the student is able to

- Identify the drawbacks of speed control of motor by conventional methods.
- Differentiate Phase controlled and chopper-controlled DC drives speed-torque characteristics merits and demerits
- Understand Ac motor drive speed–torque characteristics using different control strategies its merits and demerits
- Describe Slip power recovery schemes

UNIT - I**Control of DC Motors**

Introduction to Thyristor controlled Drives, Single Phase semi and fully controlled converters connected to d.c separately excited and d.c series motors – continuous current operation – output voltage and current waveforms – Speed and Torque expressions – Speed – Torque Characteristics- Problems on Converter fed d.c motors.

Three phase semi and fully controlled converters connected to d.c separately excited and d.c series motors – output voltage and current waveforms – Speed and Torque expressions – Speed – Torque characteristics – Problems.

UNIT - II**Four Quadrant Operation of DC Drives**

Introduction to Four quadrant operation – Motoring operations, Electric Braking – Plugging, Dynamic, and Regenerative Braking operations. Four quadrant operation of D.C motors by single phase and three phase dual converters – Closed loop operation of DC motor (Block Diagram Only)

Control of DC Motors By Choppers: Single quadrant, Two quadrant and four quadrant chopper fed dc separately excited and series motors – Continuous current operation – Output voltage and current wave forms – Speed and torque expressions – speed-torque characteristics – Problems on Chopper fed D.C Motors – Closed Loop operation (Block Diagram Only)

UNIT - III**Control of Induction Motor**

Variable voltage characteristics-Control of Induction Motor by Ac Voltage Controllers – Waveforms – speed torque characteristics.

Variable frequency characteristics-Variable frequency control of induction motor by Voltage source and current source inverter and cyclo converters- PWM control – Comparison of VSI and CSI operations – Speed torque characteristics – numerical problems on induction motor drives – Closed loop operation of induction motor drives (Block Diagram Only)

UNIT - IV**Rotor Side Control of Induction Motor**

Static rotor resistance control – Slip power recovery – Static Scherbius drive – Static Kramer Drive – their performance and speed torque characteristics – advantages, applications, problems.

UNIT - V

Control of Synchronous Motors

Separate control and self-control of synchronous motors – Operation of self-controlled synchronous motors by VSI, CSI and cyclo converters. Load commutated CSI fed Synchronous Motor – Operation – Waveforms – speed torque characteristics – Applications – Advantages and Numerical Problems – Closed Loop control operation of synchronous motor drives (Block Diagram Only), variable frequency control - Cyclo converter, PWM based VSI & CSI.

TEXT BOOKS:

1. “G K Dubey”, Fundamentals of Electric Drives, CRC Press, 2002.
2. “Vedam Subramanyam”, Thyristor Control of Electric drives, Tata McGraw Hill Publications, 1987.

REFERENCE BOOKS:

1. “S K Pillai”, A First course on Electrical Drives, New Age International (P) Ltd. 2nd Edition. 1989
2. “P. C. Sen”, Thyristor DC Drives, Wiley-Blackwell, 1981
3. “B. K. Bose”, Modern Power Electronics, and AC Drives, Pearson 2015.
4. “R. Krishnan”, Electric motor drives - modeling, Analysis and control, Prentice Hall PTR, 2001

EE613PE: WIND AND SOLAR ENERGY SYSTEMS (Professional Elective - II)**B.Tech. III Year II Sem.**

L	T	P	C
3	0	0	3

Prerequisite: Renewable Energy Systems**Course Objectives:**

- To study the physics of wind power and energy
- To understand the principle of operation of wind generators
- To know the solar power resources
- To analyze the solar photo-voltaic cells
- To discuss the solar thermal power generation
- To identify the network integration issues

Course Outcomes: At the end of this course, students will demonstrate the ability to

- Understand the energy scenario and the consequent growths of the power generate renewable energy sources.
- Understand the basic physics of wind and solar power generation.
- Understand the power electronic interfaces for wind and solar generation.
- Understand the issues related to the grid-integration of solar and wind energy systems

UNIT - I**Physics of Wind Power**

History of wind power, Indian and Global statistics, Wind physics, Betz limit ratio, stall and pitch control, Wind speed statistics-probability distributions, and Wind power-cumulative distribution functions.

UNIT - II**Wind Generator Topologies**

Review of modern wind turbine technologies, Fixed and Variable speed wind turbine, Induction Generators, Doubly-Fed Induction Generators and their characteristics, Permanent Magnet Synchronous Generators, Power electronics converters. Generator configurations, Converter Control.

UNIT - III**The Solar Resource**

Introduction, solar radiation spectra, solar geometry, Earth Sun angles, observer Sun angles, solar day length, Estimation of solar energy availability.

Solar Photovoltaic

Technologies-Amorphous, mono-crystalline, polycrystalline; V-I characteristics of a PV cell, PV module, array, Power Electronic Converters for Solar Systems, Maximum Power point Tracking (MPPT) algorithms. Converter Control.

UNIT - IV**Network Integration Issues**

Overview of grid code technical requirements. Fault ride-through for wind farms - real and reactive power regulation, voltage and frequency operating limits, solar PV and wind farm behavior during grid disturbances. Power quality issues. Power system interconnection experiences in the world. Hybrid and isolated operations of solar PV and wind systems.

UNIT - V**Solar Thermal Power Generation**

Technologies, Parabolic trough, central receivers, parabolic dish, Fresnel, solar pond, elementary analysis.

TEXT BOOKS:

1. T. Ackermann, "Wind Power in Power Systems", John Wiley and Sons Ltd., 2005.
2. G. M. Masters, "Renewable and Efficient Electric Power Systems", John Wiley and Sons, 2004.

REFERENCE BOOKS:

1. S. P. Sukhatme, "Solar Energy: Principles of Thermal Collection and Storage", McGraw Hill, 1984.
2. H. Siegfried and R. Waddington, "Grid integration of wind energy conversion systems" John Wiley and Sons Ltd., 2006.
3. G. N. Tiwari and M. K. Ghosal, "Renewable Energy Applications", Narosa Publications, 2004.
4. J. A. Duffie and W. A. Beckman, "Solar Engineering of Thermal Processes", John Wiley & Sons, 1991.

EE601PC: SIGNALS AND SYSTEMS**B.Tech. III Year II Sem.**

L	T	P	C
2	1	0	3

Course Objectives:

- This gives the basics of Signals and Systems required for all Electrical Engineering related courses.
- To understand the behavior of signal in time and frequency domain
- To understand the characteristics of LTI systems
- This gives concepts of Signals and Systems and its analysis using different transform techniques.

Course Outcomes: Upon completing this course, the student will be able to

- Differentiate various signal functions.
- Represent any arbitrary signal in time and frequency domain.
- Understand the characteristics of linear time invariant systems.
- Analyze the signals with different transform technique

UNIT - I

Signal Analysis: Analogy between Vectors and Signals, Orthogonal Signal Space, Signal approximation using Orthogonal functions, Mean Square Error, Closed or complete set of Orthogonal functions, Orthogonality in Complex functions, Classification of Signals and systems, Exponential and Sinusoidal signals, Concepts of Impulse function, Unit Step function, Signum function.

UNIT – II

Fourier series: Representation of Fourier series, Continuous time periodic signals, Properties of Fourier Series, Dirichlet's conditions, Trigonometric Fourier Series and Exponential Fourier Series, Complex Fourier spectrum.

Fourier Transforms: Deriving Fourier Transform from Fourier series, Fourier Transform of arbitrary signal, Fourier Transform of standard signals, Fourier Transform of Periodic Signals, Properties of Fourier Transform, Fourier Transforms involving Impulse function and Signum function, Introduction to Hilbert Transform.

UNIT - III

Signal Transmission through Linear Systems: Linear System, Impulse response, Response of a Linear System, Linear Time Invariant(LTI) System, Linear Time Variant (LTV) System, Transfer function of a LTI System, Filter characteristic of Linear System, Distortion less transmission through a system, Signal bandwidth, System Bandwidth, Ideal LPF, HPF, and BPF characteristics, Causality and Paley-Wiener criterion for physical realization, Relationship between Bandwidth and rise time, Convolution and Correlation of Signals, Concept of convolution in Time domain and Frequency domain, Graphical representation of Convolution.

UNIT – IV

Laplace Transforms: Laplace Transforms (L.T), Inverse Laplace Transform, Concept of Region of Convergence (ROC) for Laplace Transforms, Properties of L.T, Relation between L.T and F.T of a signal, Laplace Transform of certain signals using waveform synthesis.

Z-Transforms: Concept of Z- Transform of a Discrete Sequence, Distinction between Laplace, Fourier and Z Transforms, Region of Convergence in Z-Transform, Constraints on ROC for various classes of signals, Inverse Z-transform, Properties of Z-transforms.

UNIT - V

Sampling theorem: Graphical and analytical proof for Band Limited Signals, Impulse Sampling, Natural and Flat top Sampling, Reconstruction of signal from its samples, Effect of under sampling – Aliasing, Introduction to Band Pass Sampling.

Correlation: Cross Correlation and Auto Correlation of Functions, Properties of Correlation Functions, Energy Density Spectrum, Parsevals Theorem, Power Density Spectrum, Relation between Autocorrelation Function and Energy/Power Spectral Density Function, Relation between Convolution and Correlation, Detection of Periodic Signals in the presence of Noise by Correlation, Extraction of Signal from Noise by Filtering.

TEXT BOOKS:

1. Signals, Systems & Communications - B.P. Lathi, 2013, BSP.
2. Signals and Systems - A.V. Oppenheim, A.S. Willsky and S.H. Nawabi, 2 Ed.

REFERENCE BOOKS:

1. Signals and Systems – Simon Haykin and Van Veen, Wiley 2 Ed.,
2. Signals and Systems – A. Rama Krishna Rao, 2008, TMH
3. Fundamentals of Signals and Systems - Michel J. Robert, 2008, MGH International Edition.
4. Signals, Systems and Transforms - C. L. Philips, J. M. Parr and Eve A. Riskin, 3 Ed., 2004, PE.
5. Signals and Systems – K. Deergha Rao, Birkhauser, 2018.

EE602PC: MICROPROCESSORS & MICROCONTROLLERS**B.Tech. III Year II Sem.**

L	T	P	C
3	0	0	3

Prerequisite: Nil**Course Objectives:**

1. To familiarize the architecture of microprocessors and micro controllers
2. To provide the knowledge about interfacing techniques of bus & memory.
3. To understand the concepts of ARM architecture
4. To study the basic concepts of Advanced ARM processors

Course Outcomes: Upon completing this course, the student will be able to

1. Understands the internal architecture, organization and assembly language programming of 8086 processors.
2. Understands the internal architecture, organization and assembly language programming of 8051/controllers
3. Understands the interfacing techniques to 8086 and 8051 based systems.
4. Understands the internal architecture of ARM processors and basic concepts of advanced ARM processors.

UNIT - I:

8086 Architecture: 8086 Architecture-Functional diagram, Register Organization, Memory Segmentation, Programming Model, Memory addresses, Physical Memory Organization, Architecture of 8086, Signal descriptions of 8086, interrupts of 8086.

Instruction Set and Assembly Language Programming of 8086: Instruction formats, Addressing modes, Instruction Set, Assembler Directives, Macros, and Simple Programs involving Logical, Branch and Call Instructions, Sorting, String Manipulations.

UNIT - II:

Introduction to Microcontrollers: Overview of 8051 Microcontroller, Architecture, I/O Ports, Memory Organization, Addressing Modes and Instruction set of 8051.

8051 Real Time Control: Programming Timer Interrupts, Programming External Hardware Interrupts, Programming the Serial Communication Interrupts, Programming 8051 Timers and Counters

UNIT – III:

I/O and Memory Interface: LCD, Keyboard, External Memory RAM, ROM Interface, ADC, DAC Interface to 8051.

Serial Communication and Bus Interface: Serial Communication Standards, Serial Data Transfer Scheme, On board Communication Interfaces-I2C Bus, SPI Bus, UART; External Communication Interfaces-RS232, USB.

UNIT – IV:

ARM Architecture: ARM Processor fundamentals, ARM Architecture – Register, CPSR, Pipeline, exceptions and interrupts interrupt vector table, ARM instruction set – Data processing, Branch instructions, load store instructions, Software interrupt instructions, Program status register instructions, loading constants, Conditional execution, Introduction to Thumb instructions.

UNIT – V:

Advanced ARM Processors: Introduction to CORTEX Processor and its architecture, OMAP Processor and its Architecture.

TEXT BOOKS:

1. Advanced Microprocessors and Peripherals – A. K. Ray and K. M. Bhurchandani, TMH, 2nd Edition 2006.
2. ARM System Developers guide, Andrew N SLOSS, Dominic SYMES, Chris WRIGHT, Elsevier, 2012

REFERENCE BOOKS:

1. The 8051 Microcontroller, Kenneth. J. Ayala, Cengage Learning, 3rd Ed, 2004.
2. Microprocessors and Interfacing, D. V. Hall, TMGH, 2nd Edition 2006.
3. The 8051 Microcontrollers, Architecture and Programming and Applications -K. Uma Rao, Andhe Pallavi, Pearson, 2009.
4. Digital Signal Processing and Applications with the OMAP- L138 Experimenter, Donald Reay, WILEY 2012.

EE603PC: POWER SYSTEM PROTECTION**B.Tech. III Year II Sem.**

L	T	P	C
3	1	0	4

Pre-requisites: Power Systems-I, Power Systems-II**Course Objectives:**

- To introduce all kinds of circuit breakers and relays for protection of Generators, Transformers and feeder bus bars from Over voltages and other hazards.
- To describe neutral grounding for overall protection.
- To understand the phenomenon of Over Voltages and its classification.

Course Outcomes: At the end of the course the student will be able to:

- Compare and contrast electromagnetic, static and microprocessor-based relays
- Apply technology to protect power system components.
- Select relay settings of over current and distance relays.
- Analyze quenching mechanisms used in air, oil and vacuum circuit breakers

UNIT - I**Protective Relays**

Introduction, Need for power system protection, effects of faults, evolution of protective relays, zones of protection, primary and backup protection, essential qualities of protection, classification of protective relays and schemes, current transformers, potential transformers, basic relay terminology.

Operating Principles and Relay Construction: Electromagnetic relays, thermal relays, static relays, microprocessor based protective relays.

UNIT - II**Over-Current Protection**

Time-current characteristics, current setting, over current protective schemes, directional relay, protection of parallel feeders, protection of ring mains, Phase fault and earth fault protection, Combined earth fault and phase fault protective scheme, Directional earth fault relay.

Distance Protection: Impedance relay, reactance relay, MHO relay, input quantities for various types of distance relays, Effect of arc resistance, Effect of power swings, effect of line length and source impedance on the performance of distance relays, selection of distance relays, MHO relay with blinders, Reduction of measuring units, switched distance schemes, auto re-closing.

UNIT- III

Pilot Relaying Schemes - Wire Pilot protection, Carrier current protection.

AC Machines and Bus Zone Protection: Protection of Generators, Protection of transformers, Bus-zone protection, frame leakage protection.

UNIT - IV:**Static Relays**

Amplitude and Phase comparators, Duality between AC and PC, Static amplitude comparator, integrating and instantaneous comparators, static phase comparators, coincidence type of phase comparator, static over current relays, static directional relay, static differential relay, static distance relays, Multi input comparators, concept of Quadrilateral and Elliptical relay characteristics.

Microprocessor Based Relays: Advantages, over current relays, directional relays, distance relays.

UNIT-V:**Circuit Breakers**

Introduction, arcing in circuit breakers, arc interruption theories, re-striking and recovery voltage, resistance switching, current chopping, interruption of capacitive current, oil circuit breaker, air blast

circuit breakers, SF6 circuit breaker, operating mechanism, selection of circuit breakers, high voltage d.c. breakers, ratings of circuit breakers, testing of circuit breakers.

FUSES: Introduction, fuse characteristics, types of fuses, application of HRC fuses, discrimination.

TEXT BOOKS:

1. Badriram and D.N. Vishwakarma, Power System Protection and Switchgear, TMH 2001.
2. U.A.Bakshi, M.V.Bakshi: Switchgear and Protection, Technical Publications, 2009.

REFERENCE BOOKS:

1. C.Russel Mason – “The art and science of protective relaying, Wiley Eastern, 1995
2. L.P.Singh “Protective relaying from Electromechanical to Microprocessors”, New Age International

EE604PC: POWER SYSTEM OPERATION AND CONTROL**B.Tech. III Year II Sem.**

L	T	P	C
3	0	0	3

Pre-requisites: Power System-I, Power System-II**Course Objectives:**

- To understand real power control and operation
- To know the importance of frequency control
- To analyze different methods to control reactive power
- To understand unit commitment problem and importance of economic load dispatch
- To understand real time control of power systems

Course Outcomes: At the end of the course the student will be able to:

- Understand operation and control of power systems.
- Analyze various functions of Energy Management System (EMS) functions.
- Analyze whether the machine is in stable or unstable position.
- Understand power system deregulation and restructuring

UNIT - I**Load Flow Studies**

Introduction, Bus classification -Nodal admittance matrix - Load flow equations - Iterative methods - Gauss and Gauss Seidel Methods, Newton-Raphson Method-Fast Decoupled method-Merits and demerits of the above methods-System data for load flow study

UNIT - II**Economic Operation of Power Systems**

Distribution of load between units within a plant-Transmission loss as a function of plant generation, Calculation of loss coefficients-Distribution of load between plants.

UNIT - III**Load Frequency Control**

Introduction, load frequency problem-Megawatt frequency (or P-f) control channel, MVAR voltages (or Q-V) control channel-Dynamic interaction between P-f and Q-V loops. Mathematical model of speed-governing system-Turbine models, division of power system into control areas, P-f control of single control area (the uncontrolled and controlled cases)-P-f control of two area systems (the uncontrolled cases and controlled cases)

UNIT - IV**Power System Stability**

The stability problem-Steady state stability, transient stability and Dynamic stability-Swing equation. Equal area criterion of stability-Applications of Equal area criterion, Step by step solution of swing equation-Factors affecting transient stability, Methods to improve steady state and Transient stability, Introduction to voltage stability

UNIT - V**Computer Control of Power Systems**

Need of computer control of power systems. Concept of energy control centre (or) load dispatch centre and the functions - system monitoring - data acquisition and control. System hardware configuration – SCADA and EMS functions. Network topology – Importance of Load Forecasting and simple techniques of forecasting.

TEXT BOOKS

1. C. L. Wadhwa, Electrical Power Systems, 3rd Edn, New Age International Publishing Co., 2001.
2. D. P. Kothari and I. J. Nagrath, Modern Power System Analysis, 4th Edn, Tata McGraw Hill Education Private Limited 2011.

REFERENCE BOOKS:

1. D. P. Kothari: Modern Power System Analysis-Tata Mc Graw Hill Pub. Co. 2003.
2. Hadi Sadat: Power System Analysis –Tata Mc Graw Hill Pub. Co. 2002.

EE605PC: POWER SYSTEM LAB**B.Tech. III Year II Sem.**

L	T	P	C
0	0	2	1

Prerequisite: Power System-I, Power System-II, Power System Protection, Power System Operation and Control, Electrical Machines

Course Objectives:

- perform testing of CT, PT's and Insulator strings
- To find sequence impedances of 3- Φ synchronous machine and Transformer
- To perform fault analysis on Transmission line models and Generators.

Course Outcomes: After completion of this lab, the student will be able to

- Perform various load flow techniques
- Understand Different protection methods
- Analyze the experimental data and draw the conclusions.

The following experiments are required to be conducted as compulsory experiments:

Part - A

1. Characteristics of IDMT Over-Current Relay.
2. Differential protection of 1- Φ transformer.
3. Characteristics of Micro Processor based Over Voltage/Under Voltage relay.
4. A,B,C,D constants of a Long Transmission line
5. Finding the sequence impedances of 3- Φ synchronous machine.
6. Finding the sequence impedances of 3- Φ Transformer.

In addition to the above six experiments, at least any four of the experiments from the following list are required to be conducted.

Part - B

1. Formation of Y_{BUS} .
2. Load Flow Analysis using Gauss Seidal (GS) Method.
3. Load Flow Analysis using Fast Decoupled (FD) Method.
4. Formation of Z_{BUS} .
5. Simulation of Compensated Line

TEXT BOOKS:

1. C.L. Wadhwa: Electrical Power Systems –Third Edition, New Age International Pub. Co., 2001.
2. Hadi Sadat: Power System Analysis –Tata Mc Graw Hill Pub. Co. 2002.

REFERENCE BOOK:

1. D. P. Kothari: Modern Power System Analysis-Tata Mc Graw Hill Pub. Co. 2003.

EE606PC: MICROPROCESSORS & MICROCONTROLLERS LAB**B.Tech. III Year II Sem.**

L	T	P	C
0	0	2	1

Cycle 1: Using 8086 Processor Kits and/or Assembler (5 Weeks)

- Assembly Language Programs to 8086 to Perform
 1. Arithmetic, Logical, String Operations on 16 Bit and 32-Bit Data.
 2. Bit level Logical Operations, Rotate, Shift, Swap and Branch Operations.

Cycle 2: Using 8051 Microcontroller Kit (6 weeks)

- Introduction to IDE
 1. Assembly Language Programs to Perform Arithmetic (Both Signed and Unsigned) 16 Bit Data Operations, Logical Operations (Byte and Bit Level Operations), Rotate, Shift, Swap and Branch Instructions
 2. Time delay Generation Using Timers of 8051.
 3. Serial Communication from / to 8051 to / from I/O devices.
 4. Program Using Interrupts to Generate Square Wave 10 KHZ Frequency on P2.1 Using Timer 0 8051 in 8 bit Auto reload Mode and Connect a 1 HZ Pulse to INT1 pin and Display on Port 0. Assume Crystal Frequency as 11.0592 MHZ

Cycle 3: Interfacing I/O Devices to 8051(5 Weeks)

1. 7 Segment Display to 8051.
2. Matrix Keypad to 8051.
3. Sequence Generator Using Serial Interface in 8051.
4. 8 bit ADC Interface to 8051.
5. Triangular Wave Generator through DAC interfaces to 8051.

TEXT BOOKS:

1. Advanced Microprocessors and Peripherals by A K Ray, Tata McGraw-Hill Education, 2006
2. The 8051 *Microcontrollers*: Architecture, Programming & Applications by Dr. K. Uma Rao, Andhe Pallavi, Pearson, 2009.

EE607PC: SIGNALS AND SYSTEMS LAB**B.Tech. III Year II Sem.**

L	T	P	C
0	0	2	1

Prerequisites: Signals and Systems**Course Objectives:**

- To develop ability to analyze linear systems and signals
- To develop critical understanding of mathematical methods to analyze linear systems and signals
- To know the various transform techniques
- To analyse sampling principles

Course Outcomes: At the end of this course, students will demonstrate the ability to

- Understand the concepts of continuous time and discrete time systems.
- Analyse systems in complex frequency domain.
- Understand sampling theorem and its implications.

List of Experiments:

1. Frequency Spectrum of continuous signal
2. Frequency Spectrum of impulse signals (Time Bounded signals)
3. Frequency Response Analysis using any Software
4. Frequency Response Analysis for any Transfer Function (Preferably Transformer)
5. Write a program to generate the discrete sequences
(i) Unit step(ii) Unit impulse(iii) Ramp(iv)Periodic sinusoidal sequences.
(Plot all the sequences).
6. Find the Fourier transform of a square pulse.
(Plot its amplitude and phase spectrum).
7. Write a program to convolve two discrete time sequences. (Plot all the sequences).Verify the result by analytical calculation.
8. WriteaprogramtofindthetrigonometricFourierseriescoefficientsofarectangular periodic signal. Reconstruct the signal by combining the Fourier series coefficients with appropriate weightings.
9. Write a program to find the trigonometric and exponential Fourier series coefficients of a periodic rectangular signal. Plot the discrete spectrum of the signal.
10. Generateadiscretetimesequencebysamplingacontinuous timesignal.Showthat with sampling rates less than Nyquist rate, aliasing occurs while reconstructing the signal.
11. Write a program to find the magnitude and phase response of first order low pass and high pass filter. Plot the responses in logarithmic scale.
12. Write a program to find the response of a low pass filter and high pass filter, when a speech signal is passed through these filters.

TEXT BOOKS:

1. A. V. Oppenheim, A. S. Willsky and S. H. Nawab, "Signals and systems", Prentice Hall India, 1997.
2. J. G. Proakis and D. G. Manolakis, "Digital Signal Processing: Principles, Algorithms, and Applications", Pearson, 2006.

REFERENCE BOOKS:

1. H. P. Hsu, "Signals and systems", Schaum's series, McGraw Hill Education, 2010.
2. S. Haykin and B. V. Veen, "Signals and Systems", John Wiley and Sons, 2007.
3. A. V. Oppenheim and R. W. Schaffer, "Discrete-Time Signal Processing", Prentice Hall, 2009.
4. M. J. Robert "Fundamentals of Signals and Systems", McGraw Hill Education, 2007.
5. B. P. Lathi, "Linear Systems and Signals", Oxford University Press, 2009.

MC609: ENVIRONMENTAL SCIENCE*B.Tech. III Year II Sem.**

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Course Objectives:

- Understanding the importance of ecological balance for sustainable development.
- Understanding the impacts of developmental activities and mitigation measures
- Understanding the environmental policies and regulations

Course Outcomes: Based on this course, the Engineering graduate will understand /evaluate / develop technologies on the basis of ecological principles and environmental regulations which in turn helps in sustainable development

UNIT - I

Ecosystems: Definition, Scope and Importance of ecosystem. Classification, structure, and function of an ecosystem, Food chains, food webs, and ecological pyramids. Flow of energy, Biogeochemical cycles, Bioaccumulation, Biomagnification, ecosystem value, services and carrying capacity, Field visits.

UNIT - II

Natural Resources: Classification of Resources: Living and Non-Living resources, **water resources:** use and over utilization of surface and ground water, floods and droughts, Dams: benefits and problems. **Mineral resources:** use and exploitation, environmental effects of extracting and using mineral resources, **Land resources:** Forest resources, **Energy resources:** growing energy needs, renewable and non-renewable energy sources, use of alternate energy source, case studies.

UNIT - III

Biodiversity and Biotic Resources: Introduction, Definition, genetic, species and ecosystem diversity. Value of biodiversity; consumptive use, productive use, social, ethical, aesthetic and optional values. India as a mega diversity nation, Hot spots of biodiversity. Field visit. Threats to biodiversity: habitat loss, poaching of wildlife, man-wildlife conflicts; conservation of biodiversity: In-Situ and Ex-situ conservation. National Biodiversity act.

UNIT - IV

Environmental Pollution and Control Technologies: Environmental Pollution: Classification of pollution, **Air Pollution:** Primary and secondary pollutants, Automobile and Industrial pollution, Ambient air quality standards. **Water pollution:** Sources and types of pollution, drinking water quality standards. **Soil Pollution:** Sources and types, Impacts of modern agriculture, degradation of soil. **Noise Pollution:** Sources and Health hazards, standards, **Solid waste:** Municipal Solid Waste management, composition and characteristics of e-Waste and its management. **Pollution control technologies:** Wastewater Treatment methods: Primary, secondary and Tertiary. Overview of air pollution control technologies, Concepts of bioremediation. **Global Environmental Problems and Global Efforts:** Climate change and impacts on human environment. Ozone depletion and Ozone depleting substances (ODS). Deforestation and desertification. International conventions / Protocols: Earth summit, Kyoto protocol, and Montréal Protocol.

UNIT - V

Environmental Policy, Legislation & EIA: Environmental Protection act, Legal aspects Air Act- 1981, Water Act, Forest Act, Wild life Act, Municipal solid waste management and handling rules, biomedical waste management and handling rules, hazardous waste management and handling rules. EIA: EIA structure, methods of baseline data acquisition. Overview on Impacts of air, water, biological and Socio-economical aspects. Strategies for risk assessment, Concepts of Environmental Management Plan

(EMP). **Towards Sustainable Future:** Concept of Sustainable Development, Population and its explosion, Crazy Consumerism, Environmental Education, Urban Sprawl, Human health, Environmental Ethics, Concept of Green Building, Ecological Foot Print, Life Cycle assessment (LCA), Low carbon life style.

TEXT BOOKS:

1. Textbook of Environmental Studies for Undergraduate Courses by Erach Bharucha for University Grants Commission.
2. Environmental Studies by R. Rajagopalan, Oxford University Press.

REFERENCE BOOKS:

1. Environmental Science: towards a sustainable future by Richard T. Wright. 2008 PHL Learning Private Ltd. New Delhi.
2. Environmental Engineering and science by Gilbert M. Masters and Wendell P. Ela. 2008 PHI Learning Pvt. Ltd.
3. Environmental Science by Daniel B. Botkin & Edward A. Keller, Wiley INDIA edition.
4. Environmental Studies by Anubha Kaushik, 4th Edition, New age international publishers.
5. Text book of Environmental Science and Technology - Dr. M. Anji Reddy 2007, BS Publications.